

Dynamic Non-Bayesian Persuasion

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Canonical Bayesian Persuasion Model:

- Sender designs and commits to an experiment to influence the receiver's action.
- Applications include advertising (Rayo and Segal, 2010), litigation (Kamenica and Gentzkow, 2011), and others.

Question:

What if the receiver is **non-Bayesian** / **misspecified-Bayesian**?

- Evidence: Bhuller and Sigstad (2025), Benjamin (2019), etc.
- Can we simply replace the Bayesian receiver with a non-Bayesian one?
- **Concern:** Real information provision is often **sequential** rather than all at once.

Results Preview

1. When the receiver is non-Bayesian, the sender's value can depend on whether information is provided all at once or sequentially.
 - One-shot/static persuasion is not generally without loss.
2. The sender is indifferent between static and dynamic persuasion in any environment if and only if the receiver's updating rule is **divisible** (Cripps, 2018).

divisible: given multiple signals, the following two procedures give the same posterior:

1. updating the prior using all signals simultaneously;
2. updating the prior using each signal sequentially.

Persuasion environment: $\langle \Theta, p, A, u, v \rangle$

- Θ : finite state space
 - p : full-support prior over Θ
- A : compact metrizable action space
- $u, v : A \times \Theta \rightarrow \mathbb{R}$: receiver's and sender's utility functions
 - u and v are continuous.

Model: Experiment and Updating Rule

$\sigma = \langle S, (\sigma_\theta)_{\theta \in \Theta} \rangle$: a Blackwell experiment

- S : finite set of signals (fixed)
- $\sigma_\theta \in \Delta(S)$: distribution over S given state θ

Σ : set of all experiments with the fixed signal space S

$\mu : \Sigma \times \Delta(\Theta) \rightarrow \Delta(\Theta)^S$: the receiver's updating rule

- μ_B : Bayesian updating.

Assume the sender is Bayesian, but the receiver may not be.

Systematic Distortions

- $\Theta_r := \{\theta \in \Theta : r(\theta) > 0\}$: support of belief r .

Definition (De Clippel and Zhang, 2022)

An updating rule μ is a **systematic distortion** if there exists a **distortion rule** $D := (D_p)_{p \in \Delta(\Theta)}$ such that $D_p : \Delta(\Theta_p) \rightarrow \Delta(\Theta)$ and, for any experiment σ and any signal realization s satisfying $\sum_{\theta \in \Theta} \sigma_\theta(s) p(\theta) > 0$,

$$\mu(\sigma, p)(\cdot | s) = D_p(\mu_B(\sigma, p)(\cdot | s)).$$

Assume the receiver's updating rule is a systematic distortion.

Example: Grether (1980)'s α - β Model

$$\mu(\sigma, p)(\theta \mid s) = \frac{p(\theta)^{\alpha} \sigma_{\theta}(s)^{\beta}}{\sum_{\theta' \in \Theta} p(\theta')^{\alpha} \sigma_{\theta'}(s)^{\beta}}$$

- $\alpha \in (0, 1]$: $\alpha < 1$ corresponds to base-rate neglect.
- $\beta \in (0, 1]$: $\beta < 1$ corresponds to underreaction to new information.

Distortion rule:

$$D_p(q)(\theta) = \begin{cases} \frac{p(\theta)^{\alpha-\beta} q(\theta)^{\beta}}{\sum_{\theta' \in \Theta_p} p(\theta')^{\alpha-\beta} q(\theta')^{\beta}} & \text{if } \theta \in \Theta_p, \\ 0 & \text{if } \theta \notin \Theta_p, \end{cases}$$

where $q \in \Delta(\Theta_p)$ is the Bayesian posterior.

Static Persuasion: Timeline

1. The sender chooses an experiment σ .
2. After observing σ and the realized signal s , the receiver forms a posterior belief $D_p(\mu_B(\sigma, p)(\cdot | s))$.
3. The receiver takes an action $a \in A$ to maximize her expected utility given the posterior belief.

Solution (De Clippel and Zhang, 2022): concavification of the modified indirect utility.

Dynamic Persuasion: Timeline

Parsimonious two-step dynamic persuasion model:

1. The sender chooses a first-step experiment σ^1 and a collection of second-step experiments $\{\sigma_{s_1}^2\}_{s_1 \in S}$.
 - $\sigma_{s_1}^2$ is used after the first-stage signal realization s_1
2. After observing σ^1 and its realization s_1 , the receiver updates her belief from p to $D_p(q)$.
 - $q := \mu_B(\sigma^1, p)(\cdot \mid s_1)$
3. After observing $\sigma_{s_1}^2$ and its realization s_2 , the receiver updates her belief from $D_p(q)$ to

$$\underbrace{D_{D_p(q)}}_{\text{distortion with "prior" } D_p(q)} \left(\underbrace{\mu_B(\sigma_{s_1}^2, D_p(q))(\cdot \mid s_2)}_{\text{Bayesian posterior with "prior" } D_p(q)} \right).$$

4. The receiver chooses an action $a \in A$.

Issue: hard to solve in general.

Definition (Informal; Cripps, 2018)

An updating rule is **divisible** if, for any prior and any sequence of signals, the following two procedures yield the same posterior belief:

- processing all signals simultaneously;
- processing the signals sequentially, using the intermediate posterior as the next prior.

Theorem

Suppose the receiver's updating rule is a systematic distortion that satisfies regularity conditions. Then, TFAE:

- 1. The receiver's updating rule is divisible.*
- 2. The sender is indifferent between static and dynamic persuasion in every persuasion environment.*

► regularity conditions

Application: α - β Model

Grether's α - β rule: with $\alpha, \beta \in (0, 1]$,

$$\mu(\sigma, p)(\theta \mid s) = \frac{p(\theta)^{\alpha} \sigma_{\theta}(s)^{\beta}}{\sum_{\theta' \in \Theta} p(\theta')^{\alpha} \sigma_{\theta'}(s)^{\beta}}$$

Corollary

Suppose the receiver's belief updating rule is given by Grether's α - β rule. Then the sender is indifferent between static and dynamic persuasion in every environment if and only if $\alpha = 1$.

- The α - β rule is divisible iff $\alpha = 1$

Intuition: judge–prosecutor example in KG

- $\Theta = \{0, 1\}$
 - 0: defendant is innocent, 1: defendant is guilty
 - $p := \Pr(\theta = 1) < 1/2$
- $A = \{0, 1\}$
 - 0: acquit, 1: convict
- $u(a, \theta) = \mathbb{1}\{a = \theta\}$
- $v(a, \theta) = a$

Threshold receiver belief: $q' = 1/2$

- $\alpha < 1 \implies$ the receiver's belief drifts towards $1/2$ even with no info in the first step.

Analyst's modeling tradeoff

- Focusing on geometric underreaction ($\alpha = 1, \beta \in (0, 1)$) can justify static persuasion models.
- Base-rate neglect ($\alpha < 1$) makes the timing of information provision payoff-relevant, so one-shot persuasion is generally not without loss.

Static Bayesian and non-Bayesian persuasion

- Kamenica and Gentzkow (2011); Rayo and Segal (2010); De Clippel and Zhang (2022)
- **Contribution:** clarifying when the model is WLOG

Concurrent work on dynamic non-Bayesian persuasion

- Azrieli and Das (2025)
 - Receiver with linear underreaction $\implies$ dynamic persuasion can $\uparrow$ sender's payoff
- **Contribution:** complete characterization of updating rules

Conclusion

- Tractable static persuasion framework is without loss if and only if the receiver's updating rule is divisible.
- Non-divisible updating rules require explicit modeling of the timing of information provision, but it is hard to solve in general.

Regular Distortions

Definition

A distortion rule D is **regular** if it satisfies:

1. **Non-decreasing support:** $\Theta_q \subseteq \Theta_{D_p(q)}$ for all $p \in \Delta^\circ(\Theta)$ and $q \in \Delta(\Theta)$.
2. **Continuity:** The map $(p, q) \mapsto D_p(q)$ from $\Delta^\circ(\Theta) \times \Delta(\Theta)$ to $\Delta(\Theta)$ is continuous.
3. **Injectivity:** D_p is one-to-one for every $p \in \Delta^\circ(\Theta)$.
4. **Prior independence under certainty:** For any full-support beliefs p, q ,

$$D_p(\delta_\theta) = D_{D_p(q)}(\delta_\theta) \quad \text{for all } \theta \in \Theta_{D_p(q)}.$$

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